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## Institute of Computer Science Academy of Sciences of the Czech Republic

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# A not-a-priori-exponential necessary and sufficient condition for regularity of interval matrices 

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Abstract:
We describe a not-a-priori-exponential necessary and sufficient condition for regularity of interval matrices which is an easy consequence of an earlier result on interval linear equations.


Keywords:
Interval matrix, regularity, necessary and sufficient condition.4]

[^0]Checking regularity of interval matrices is a known NP-hard problem. Forty necessary and sufficient regularity conditions are summed up in [2]; all of them are exponential because they explicitly or implicitly contain the quantifier "for each $z \in\{-1,1\}^{n}$ ". The condition given below is, to these authors' knowledge, the first ever published not-a-priori-exponential regularity condition because instead of $\{-1,1\}^{n}$ it employs only a subset $Z$ of it. Cardinality of the set $Z$ varies with the data, but its minimal value is 1 . Notation used: $e_{j}$ is the $j$ th column of the $n \times n$ identity matrix, $e=(1,1, \ldots, 1)^{T} \in \mathbb{R}^{n}, \operatorname{diag}(z)$ is the $n \times n$ diagonal matrix with diagonal vector $z$ and for an $x \in \mathbb{R}^{n}, \operatorname{sgn}(x)$ is defined by $(\operatorname{sgn}(x))_{i}=1$ if $x_{i} \geq 0$ and $(\operatorname{sgn}(x))_{i}=-1$ otherwise.

Theorem 1. An $n \times n$ interval matrix $\boldsymbol{A}=\left[A_{c}-\Delta, A_{c}+\Delta\right]$ is regular if and only if $A_{c}$ is nonsingular and there exists a subset $Z$ of $\{-1,1\}^{n}$ having the following properties:
(a) $\operatorname{sgn}\left(A_{c}^{-1} e\right) \in Z$,
(b) for each $z \in Z$ the inequalities

$$
\begin{align*}
\left(Q A_{c}-I\right) \operatorname{diag}(z) & \geq|Q| \Delta  \tag{0.1}\\
\left(Q A_{c}-I\right) \operatorname{diag}(-z) & \geq|Q| \Delta \tag{0.2}
\end{align*}
$$

have matrix solutions $Q_{z}$ and $Q_{-z}$, respectively,
(c) if $z \in Z, Q_{-z} e \leq Q_{z} e$, and $\left(Q_{-z} e\right)_{j}\left(Q_{z} e\right)_{j} \leq 0$ for some $j$, then $z-2 z_{j} e_{j} \in Z$.

Proof. "If": The assumptions (a)-(c) imply that the three assumptions of Theorem 3 in [3] are met for the system of interval linear equations $\boldsymbol{A} x=[e, e]$ whose solution set in virtue of the same theorem is bounded, hence $\boldsymbol{A}$ is regular. "Only if": If $\boldsymbol{A}$ is regular, then (a) and (c) are satisfied for $Z=\{-1,1\}^{n}$ and for each $z \in\{-1,1\}^{n}$ the equations

$$
\begin{aligned}
\left(Q A_{c}-I\right) \operatorname{diag}(z) & =|Q| \Delta \\
\left(Q A_{c}-I\right) \operatorname{diag}(-z) & =|Q| \Delta
\end{aligned}
$$

have (even unique) solutions, see [2].
Hence we can also formulate the theorem in the following way:
Theorem 2. An $n \times n$ interval matrix $\boldsymbol{A}=\left[A_{c}-\Delta, A_{c}+\Delta\right]$ is regular if and only if $A_{c}$ is nonsingular and there exists a subset $Z$ of $\{-1,1\}^{n}$ having the following properties:
(a) $\operatorname{sgn}\left(A_{c}^{-1} e\right) \in Z$,
(b) for each $z \in Z$ the equations

$$
\begin{align*}
\left(Q A_{c}-I\right) \operatorname{diag}(z) & =|Q| \Delta  \tag{0.3}\\
\left(Q A_{c}-I\right) \operatorname{diag}(-z) & =|Q| \Delta \tag{0.4}
\end{align*}
$$

have matrix solutions $Q_{z}$ and $Q_{-z}$, respectively,
(c) if $z \in Z, Q_{-z} e \leq Q_{z} e$, and $\left(Q_{-z} e\right)_{j}\left(Q_{z} e\right)_{j} \leq 0$ for some $j$, then $z-2 z_{j} e_{j} \in Z$.

Notice that if $z \in\{-1,1\}^{n}$, then $z-2 z_{j} e_{j} \in\{-1,1\}^{n}$ (in (c)), so that $Z \subseteq\{-1,1\}^{n}$; thus $Z$ is defined recursively by (a) and (c). In practical computations, equations (0.3), (0.4) are solved instead of inequalities (0.1), (0.2) as it was done in the function qzmatrix, using the subfunction absvaleqn, in [4].

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    ${ }^{4}$ Above: logo of interval computations and related areas (depiction of the solution set of the system $[2,4] x_{1}+[-2,1] x_{2}=[-2,2],[-1,2] x_{1}+[2,4] x_{2}=[-2,2]($ Barth and Nuding [1] $\left.)\right)$.

