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# The Conjecture " $\mathrm{P} \neq \mathrm{NP}$ " and Overestimation in Bounding Solutions of Perturbed Linear Equations 

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Technical report No. 644

June 15, 1995

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# The Conjecture " $\mathrm{P} \neq \mathrm{NP}$ " and Overestimation in Bounding Solutions of Perturbed Linear Equations ${ }^{1}$ 

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#### Abstract

It is proved that a classical bound on solutions of perturbed systems of linear equations may yield arbitrarily large polynomial overestimations for arbitrarily narrow perturbations provided the conjecture $\mathrm{P} \neq \mathrm{NP}$ is true.


## Keywords

Linear equations, perturbation, error bound, overestimation, $\mathrm{P} \neq \mathrm{NP}$

[^0]
## 1 Introduction

For a system of linear equations

$$
\begin{equation*}
A x=b \tag{1.1}
\end{equation*}
$$

with an $n \times n$ nonsingular matrix $A$, consider a family of perturbed systems

$$
\begin{equation*}
A^{\prime} x^{\prime}=b^{\prime} \tag{1.2}
\end{equation*}
$$

with data satisfying

$$
\begin{equation*}
\left|A^{\prime}-A\right| \leq \Delta \tag{1.3}
\end{equation*}
$$

and

$$
\begin{equation*}
\left|b^{\prime}-b\right| \leq \delta \tag{1.4}
\end{equation*}
$$

where $\Delta \geq 0$ and $\delta \geq 0$ are an $n \times n$ perturbation matrix and a perturbation $n$ vector, respectively, and the inequalities are understood componentwise. The classical numerical argument using Neumann series shows that if the spectral condition

$$
\begin{equation*}
\varrho\left(\left|A^{-1}\right| \Delta\right)<1 \tag{1.5}
\end{equation*}
$$

holds, then each $A^{\prime}$ satisfying (1.3) is nonsingular and the solution of each system (1.2) with data (1.3), (1.4) satisfies

$$
\begin{equation*}
\left|x^{\prime}-x\right| \leq d \tag{1.6}
\end{equation*}
$$

where

$$
\begin{equation*}
d=\left(I-\left|A^{-1}\right| \Delta\right)^{-1}\left|A^{-1}\right|(\Delta|x|+\delta) \tag{1.7}
\end{equation*}
$$

and $I$ is the unit matrix (see Skeel [8] or Rump [6]). To keep the paper self-contained, we give here another simple proof of this result: for the solutions $x, x^{\prime}$ of (1.1), (1.2) under (1.3), (1.4) we have

$$
\begin{aligned}
\left|x^{\prime}-x\right| & =\left|A^{-1} A\left(x^{\prime}-x\right)\right| \leq\left|A^{-1}\right| \cdot\left|\left(A-A^{\prime}\right)\left(x^{\prime}-x\right)+\left(A-A^{\prime}\right) x+b^{\prime}-b\right| \\
& \leq\left|A^{-1}\right|\left(\Delta\left|x^{\prime}-x\right|+\Delta|x|+\delta\right),
\end{aligned}
$$

hence

$$
\left(I-\left|A^{-1}\right| \Delta\right)\left|x^{\prime}-x\right| \leq\left|A^{-1}\right|(\Delta|x|+\delta)
$$

and premultiplying this inequality by $\left(I-\left|A^{-1}\right| \Delta\right)^{-1}$, which is nonnegative in view of (1.5), we obtain (1.6), where $d$ is given by (1.7).

The quality of the estimation (1.6) has been paid little attention in the literature. Obviously, the bound $d$ is exact if $\Delta=0$. In fact, in this case, for each $i \in\{1, \ldots, n\}$, if we take $b_{j}^{\prime}=b_{j}+\delta_{j}$ if $\left(A^{-1}\right)_{i j} \geq 0$ and $b_{j}^{\prime}=b_{j}-\delta_{j}$ otherwise, then $b^{\prime}$ satisfies (1.4) and for the solution $x^{\prime}$ of $A x^{\prime}=b^{\prime}$ we have

$$
\left|x_{i}^{\prime}-x_{i}\right|=\sum_{j}\left|\left(A^{-1}\right)_{i j}\right| \delta_{j}=d_{i},
$$

hence the bound is achieved. However, this argument fails in the case $\Delta \neq 0$. In this paper we show that the famous conjecture " $\mathrm{P} \neq \mathrm{NP}$ " (see Garey and Johnson [1] for details) shreds a surprising light on this problem: in the main result to follow we show that if the conjecture is true, then the formula (1.6) may yield an arbitrarily large polynomial overestimation for arbitrarily narrow perturbations $\Delta, \delta$. Hence, the conjecture deeply penetrates the area of numerical linear algebra as well.

## 2 Main result

We shall use the subordinate matrix norm

$$
\|\Delta\|_{m}=\max _{i, j}\left|\Delta_{i j}\right|
$$

and the vector norm

$$
\|\delta\|_{\infty}=\max _{i}\left|\delta_{i}\right|
$$

Our main result is formulated as follows:
Theorem 1 If $P \neq N P$, then for each rational $\varepsilon>0, \eta>0, \alpha>0$ and for each integer $k \geq 0$ there exist $n \times n$ matrices $A, \Delta \geq 0$ and n-vectors $b, \delta \geq 0$ for some $n \geq 2$ such that

$$
\begin{gather*}
\varrho\left(\left|A^{-1}\right| \Delta\right)=0  \tag{2.1}\\
\|\Delta\|_{m}=\varepsilon  \tag{2.2}\\
\|\delta\|_{\infty}=\eta \tag{2.3}
\end{gather*}
$$

hold and the solution $x^{\prime}$ of each system (1.2) with data (1.3), (1.4) satisfies

$$
\begin{equation*}
\left|x_{1}^{\prime}-x_{1}\right|+\alpha n^{k} \leq d_{1} \tag{2.4}
\end{equation*}
$$

where $x$ is the solution of (1.1) and $d$ is given by (1.7).
Proof. Assume to the contrary that it is not so, so that there exist rational numbers $\varepsilon>0, \eta>0, \alpha>0$ and an integer $k \geq 0$ such that for each $n \geq 2$ and all $n \times n$ matrices $A, \Delta \geq 0$ and all $n$-vectors $b, \delta \geq 0$ satisfying (2.1)-(2.3) we have

$$
\begin{equation*}
\left|x_{1}^{\prime}-x_{1}\right|+\alpha n^{k}>d_{1} \tag{2.5}
\end{equation*}
$$

for the solution $x^{\prime}$ of some system (1.2) with data (1.3), (1.4).
Take an arbitrary $m \times m M C$-matrix $\tilde{A}, m \geq 1$, i.e. a matrix $\tilde{A}$ satisfying $\tilde{A}_{i i}=m$ and $\tilde{A}_{i j} \in\{0,-1\}$ if $i \neq j(i, j=1, \ldots, m) ; \tilde{A}$ is nonsingular (cf. [4]). Let us define

$$
\begin{align*}
& A=\left(\begin{array}{cc}
\frac{\varepsilon \eta}{\gamma} & 0^{T} \\
0 & \tilde{A}^{-1}
\end{array}\right)  \tag{2.6}\\
& \Delta=\left(\begin{array}{cc}
0 & \varepsilon e^{T} \\
0 & 0
\end{array}\right) \tag{2.7}
\end{align*}
$$

where $\gamma=\alpha(m+1)^{k}$ and $e=(1, \ldots, 1)^{T} \in \mathbb{R}^{m}$ (hence $A$ and $\Delta$ are of size $(m+1) \times$ $(m+1))$, and let

$$
\begin{equation*}
b=\binom{0}{0} \tag{2.8}
\end{equation*}
$$

and

$$
\begin{equation*}
\delta=\binom{0}{\eta e} \tag{2.9}
\end{equation*}
$$

be $(m+1)$-dimensional vectors. Then

$$
\left|A^{-1}\right| \Delta=\left(\begin{array}{cc}
0 & \frac{\gamma}{\eta} e^{T} \\
0 & 0
\end{array}\right)
$$

hence (2.1), (2.2) and (2.3) hold, the solution of (1.1) is $x=0$ and for

$$
\bar{x}_{1}:=\max \left\{x_{1}^{\prime} ; x^{\prime} \text { solves (1.2) under (1.3), (1.4) }\right\}
$$

we have (if we denote $\tilde{x}=\left(x_{2}, x_{3}, \ldots, x_{m}\right)^{T}$ ) that

$$
\begin{aligned}
\bar{x}_{1} & =\frac{\gamma}{\varepsilon \eta} \max \left\{\varepsilon e^{T}|\tilde{x}| ;-\eta e \leq \tilde{A}^{-1} \tilde{x} \leq \eta e\right\} \\
& =\gamma \max \left\{\|\tilde{A} x\|_{1} ; x_{j} \in\{-1,1\} \text { for each } j\right\} \\
& =\gamma\|\tilde{A}\|_{\infty, 1}
\end{aligned}
$$

(see Golub and van Loan [2] for definition of $\|\tilde{A}\|_{\infty, 1}$ ), and in a similar way for

$$
\underline{x}_{1}:=\min \left\{x_{1}^{\prime} ; x^{\prime} \text { solves }(1.2) \text { under }(1.3),(1.4)\right\}
$$

we obtain

$$
\underline{x}_{1}=-\gamma\|\tilde{A}\|_{\infty, 1} .
$$

Let us now compute $d$ by (1.7). Then in view of (2.5) we have (since $x=0$ ) that

$$
\gamma\|\tilde{A}\|_{\infty, 1} \geq\left|x_{1}^{\prime}\right|>d_{1}-\alpha(m+1)^{k}=d_{1}-\gamma
$$

hence

$$
\begin{equation*}
d_{1}<\gamma\left(\|\tilde{A}\|_{\infty, 1}+1\right) \tag{2.10}
\end{equation*}
$$

But in view of (1.6) and of $x=0$ we also have

$$
\begin{equation*}
\gamma\|\tilde{A}\|_{\infty, 1}=\bar{x}_{1} \leq d_{1} \tag{2.11}
\end{equation*}
$$

hence (2.10) and (2.11) give

$$
\begin{equation*}
\|\tilde{A}\|_{\infty, 1} \leq \frac{d_{1}}{\gamma}<\|\tilde{A}\|_{\infty, 1}+1 \tag{2.12}
\end{equation*}
$$

Since the $M C$-matrix $\tilde{A}$ is integer by definition, the number

$$
\|\tilde{A}\|_{\infty, 1}=\max \left\{\|\tilde{A} x\|_{1} ; x_{j} \in\{-1,1\} \text { for each } j\right\}
$$

is also integer, hence from (2.12) we finally obtain

$$
\begin{equation*}
\|\tilde{A}\|_{\infty, 1}=\left[\frac{d_{1}}{\gamma}\right] \tag{2.13}
\end{equation*}
$$

where [...] denotes the integer part.
Summing up, we have proved the following: given an $M C$-matrix $\tilde{A}$, if we construct $A, \Delta, b$ and $\delta$ by (2.6)-(2.9) and then compute $d$ by (1.7), then (2.13) holds. Since all these computations can be done in polynomial time (Schrijver [7]), we have a polynomial-time algorithm for computing $\|\tilde{A}\|_{\infty, 1}$ for an $M C$-matrix $\tilde{A}$. However, computing $\|\tilde{A}\|_{\infty, 1}$ was proved to be NP-hard for $M C$-matrices $\tilde{A}$ ([5], Corollary 7, which is a simple consequence of Theorem 2.6 in [3]). Hence, an existence of a polynomialtime algorithm for solving an NP-hard problem implies $\mathrm{P}=\mathrm{NP}$, which contradicts our assumption.

## 3 Concluding remarks

We have proved that if $\mathrm{P} \neq \mathrm{NP}$, then for arbitrarily narrow perturbations (2.2), (2.3) the formula (1.7) may yield a catastrophic overestimation (2.4). This, of course, is a worst-case-type result. The conjecture " $\mathrm{P} \neq \mathrm{NP}$ " has not been proved to date, but it is widely believed to be true (Garey and Johnson [1]). In any case, we can see that the conjecture is closely related to one of the basic problems in numerical linear algebra; if the assertion concerning the overestimation (2.4) is not true, then a simple algorithm based on formulae (2.6), (2.7), (2.8), (2.9), (1.7) and (2.13) gives a polynomial-time algorithm for solving an NP-hard problem, thereby also solving in polynomial time all the problems in the class NP.

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