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Abstract

In the paper mixed-hybrid approximation of the potential fluid flow problem based on the prismatic discretization of the domain is presented. Trilateral prismatic elements with vertical faces and nonparallel bases suitable for the modelling of the real geological circumstances are considered. The set of linearly independent vector basis functions is defined, existence and uniqueness of the approximate solution from the resulting symmetric indefinite system are examined. Possible approaches in the solution of the discretized system are discussed.

Keywords

potential flow problem in porous media, mixed-hybrid formulation, general prismatic elements, symmetric indefinite linear systems.

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1 Introduction

The solution of underground water flow problem in the real conditions must reflect complex geological structure of sedimented minerals. Layers of the stratified rocks with substantially different physical properties must be modelled using the appropriate discretization of the geological region. These geological characteristics can be correspondingly described by the mixed-hybrid finite element method using trilateral prismatic elements with vertical faces and generally nonparallel bases.

An outline of the paper is as follows. First, we introduce the mathematical formulation of the problem. In Section 2, we consider the mixed-hybrid formulation. Finite-dimensional approximation, existence and uniqueness of the approximate solution are derived in Section 3. Finally, different approaches in the solution of the discretized linear system with symmetric indefinite matrix are discussed and promising ways are proposed.

Let Ω be a bounded domain in R^3 with a Lipschitz continuous boundary $\partial\Omega$. The potential fluid flow in a saturated porous media can be modelled by the velocity $\mathbf{u}$ given by Darcy's law

$$\mathbf{u} = -\mathbf{A}^{-1}\nabla p, \tag{1.1}$$

where p is the piezometric potential (fluid pressure) and $\mathbf{A}^{-1}$ is symmetric and uniformly positive definite second rank tensor of hydraulic permeability of the porous medium, i.e. there exists a positive constant α_0 such that

$$\alpha_0\|\xi\|_2^2 \leq (\mathbf{A}^{-1}(\mathbf{x})\xi, \xi)$$

holds for all $\xi \in R^3$ and almost all $\mathbf{x} \in \Omega$. Further we assume $[\mathbf{A}^{-1}(\mathbf{x})]_{ij} \in L^\infty(\Omega)$ for all $i, j \in \{1, 2, 3\}$. Consider also the continuity equation for the incompressible flow

$$\nabla \cdot \mathbf{u} = q, \tag{1.2}$$

where q represents the density of potential sources in the medium. The boundary conditions are given by

$$p = p_D \quad \text{on} \quad \partial\Omega_D, \tag{1.3}$$

$$\mathbf{u} \cdot \mathbf{n} = -\mathbf{A}^{-1}\nabla p \cdot \mathbf{n} = u_N \quad \text{on} \quad \partial\Omega_N, \tag{1.4}$$

where $\partial\Omega = \overline{\partial\Omega_D} \cup \overline{\partial\Omega_N}$ are such that $\partial\Omega_D \cap \partial\Omega_N = \emptyset$ and $\mathbf{n}$ is the outward normal vector defined (almost everywhere) on the boundary $\partial\Omega$.

A remark on the notation. We denote by $L^2(\Omega)$ the Lebesgue space defined as

$$L^2(\Omega) = \{\phi : \ \Omega \to R; \ \int_\Omega |\phi|^2 d\mathbf{x} < \infty\}$$

with the scalar product $(\phi_1, \phi_2)_{0,\Omega} = \int_\Omega \phi_1\phi_2 d\mathbf{x}$ and the standard norm $\|\phi\|_{0,\Omega} = (\phi, \phi)_{0,\Omega}^{\frac{1}{2}}$. Further we denote by $\mathbf{L}^2(\Omega)$ the Lebesgue space of vector valued functions $\mathbf{v}$, where the components v_i, $i = 1, \ldots, 3$ belong to space $L^2(\Omega)$ and consider the Sobolev space

$$H^1(\Omega) = \{\varphi \in L^2(\Omega); \nabla\varphi \in \mathbf{L}^2(\Omega)\}$$

with the scalar product $(\varphi_1, \varphi_2)_{1,\Omega} = \int_\Omega [\varphi_1 \varphi_2 + \nabla\varphi_1 \cdot \nabla\varphi_2] d\mathbf{x}$ and the norm $\|\varphi\|_{1,\Omega} = (\varphi, \varphi)^{\frac{1}{2}}_{1,\Omega}$. We introduce the space of the vector valued functions

$$\mathbf{H}(div, \Omega) = \{\mathbf{v} \in \mathbf{L}^2(\Omega);\ \nabla \cdot \mathbf{v} \in L^2(\Omega)\}$$

with the norm defined as $\| \mathbf{v} \|_{div,\Omega} = \left(\| \mathbf{v} \|^2_{0,\Omega} + \| \nabla \cdot \mathbf{v} \|^2_{0,\Omega} \right)^{\frac{1}{2}}$. We shall also denote the bilinear form $< \phi, \mu >_{\partial\Omega} = \int_{\partial\Omega} \phi \mu dS$, where ϕ and μ are the functions from $L^2(\partial\Omega)$.

2 Mixed-hybrid formulation of the problem

Denote the $\mathcal{E}_h$ the collection of subdomains of the domain Ω and the collection of faces of subdomains $e \in \mathcal{E}_h$ which are not adjacent to the boundary $\partial\Omega_D$ by $\Gamma_h = \cup_{e\in\mathcal{E}_h} \partial e - \partial\Omega_D$, where h is the discretization parameter (see [4])

$$h = \max_{e\in\mathcal{E}_h} \{\text{diam } e\}.$$

Denote the restriction of any function on subdomain $e \in \mathcal{E}_h$ by the superscript e, i.e. $\phi^e = \phi|_e$. Let us introduce the functional spaces defined on the $\mathcal{E}_h$ and Γ_h. Let $\mathbf{H}(div, \mathcal{E}_h)$ be the space of square integrable vector functions $\mathbf{v} \in \mathbf{L}^2(\Omega)$, whose divergences are square integrable on every subdomain $e \in \mathcal{E}_h$, i.e.

$$\mathbf{H}(div, \mathcal{E}_h) = \{\mathbf{v} \in \mathbf{L}^2(\Omega);\ \nabla \cdot \mathbf{v}^e \in L^2(e),\ \forall e \in \mathcal{E}_h\} \tag{2.1}$$

with the norm given as

$$\| \mathbf{v} \|_{div,\mathcal{E}_h} = [\| \mathbf{v} \|^2_{0,\Omega} + \sum_{e\in\mathcal{E}_h} \| \nabla \cdot \mathbf{v}^e \|^2_{0,e}]^{\frac{1}{2}}, \tag{2.2}$$

We consider also the space of traces

$$H^{\frac{1}{2}}_D(\Gamma_h) = \{\mu : \Gamma_h \to R;\ \exists\varphi \in H^1_D(\Omega),\ \mu = \gamma_h \varphi\}, \tag{2.3}$$

where the space $H^1_D(\Omega)$ is defined as $H^1_D(\Omega) = \{\varphi \in H^1(\Omega);\ \gamma\varphi = 0 \text{ on } \partial\Omega_D\}$ and $\gamma\varphi = \varphi|_{\partial\Omega}$ is the trace of the function $\varphi \in H^1(\Omega)$ on the boundary $\partial\Omega$; $\gamma_h \varphi = \varphi|_{\Gamma_h}$ is the trace of the function $\varphi \in H^1(\Omega)$ on the structure of faces Γ_h. The space $H^{\frac{1}{2}}_D(\Gamma_h)$ is equipped with the norm

$$\| \mu \|_{\frac{1}{2},\Gamma_h} = \inf_{\varphi\in H^1_D(\Omega)} \{|\varphi|_{1,\Omega};\ \gamma_h\varphi = \mu \text{ on } \Gamma_h\}, \tag{2.4}$$

where $|\varphi|_{1,\Omega}$ denotes the seminorm $|\varphi|_{1,\Omega} = (\nabla\varphi, \nabla\varphi)^{\frac{1}{2}}_{0,\Omega}$.

Thus, the mixed-hybrid formulation of the problem (1.1), (1.2) with boundary conditions (1.3), (1.4) and the discretization $\mathcal{E}_h$ of the domain Ω can be stated as follows (see also [12], [9]):

$$find\ \ (\mathbf{u}, p, \lambda) \in \mathbf{H}(div, \mathcal{E}_h) \times L^2(\Omega) \times H^{\frac{1}{2}}_D(\Gamma_h)\ such\ that:$$

$$\sum_{e\in\mathcal{E}_h}\{(\mathbf{A}^{-1}\mathbf{u}^e,\mathbf{v}^e)_{0,e}-(p^e,\nabla\cdot\mathbf{v}^e)_{0,e}+<\lambda^e,\mathbf{n}^e\cdot\mathbf{v}^e>_{\partial e\cap\Gamma_h}\}= \tag{2.5}$$

$$=\sum_{e\in\mathcal{E}_h}<p_D^e,\mathbf{n}^e\cdot\mathbf{v}^e>_{\partial e\cap\partial\Omega_D},\quad \forall\mathbf{v}\in\mathbf{H}(div,\mathcal{E}_h);$$

$$-\sum_{e\in\mathcal{E}_h}(\nabla\cdot\mathbf{u}^e,\phi^e)_{0,e}=-\sum_{e\in\mathcal{E}_h}(q^e,\phi^e)_{0,e},\quad \forall\phi^e\in L_2(\Omega); \tag{2.6}$$

$$\sum_{e\in\mathcal{E}_h}<\mathbf{n}^e\cdot\mathbf{u}^e,\mu^e>_{\partial e}=\sum_{e\in\mathcal{E}_h}<u_N^e,\mu^e>_{\partial e\cap\partial\Omega_N},\quad \forall\mu\in H_D^{\frac{1}{2}}(\Gamma_h). \tag{2.7}$$

3 Discretization of the domain and finite - dimensional approximation

In this section we introduce the discretization of the domain Ω and the lowest order finite-dimensional approximation of (2.5)-(2.7).

Assume from now that the domain Ω is polyhedron and is subdivided in a collection of subdomains, such that every subdomain is a trilateral prism with the suitable chosen vertices $\mathbf{x}_1,\mathbf{x}_2,\mathbf{x}_3,\mathbf{x}_4,\mathbf{x}_5,\mathbf{x}_6$

$$\begin{aligned}
\mathbf{x}_1 &= (x_1,y_1,z_1)\ , & \mathbf{x}_2 &= (x_2,y_2,z_2)\ , & \mathbf{x}_3 &= (x_3,y_3,z_3)\ ,\\
\mathbf{x}_4 &= (x_1,y_1,z_4)\ , & \mathbf{x}_5 &= (x_2,y_2,z_5)\ , & \mathbf{x}_6 &= (x_3,y_3,z_6)\ .
\end{aligned}$$

We allow also the elements that approximate boundary of the domain, such that for some $i\in\{1,2,3\}$ is $\mathbf{x}_i=\mathbf{x}_{i+3}$, or there exist $i,j\in\{1,2,3\},\ i\neq j$ such that $\mathbf{x}_i=\mathbf{x}_{i+3}$ and $\mathbf{x}_j=\mathbf{x}_{j+3}$.

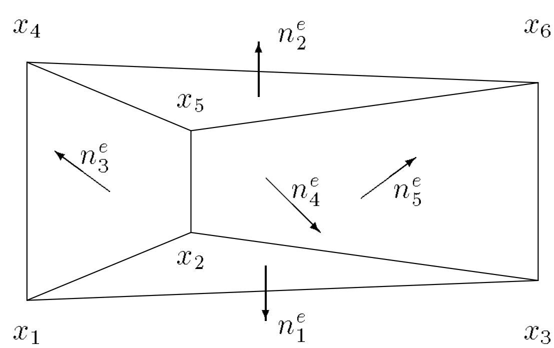

FIG 3.1

We will assume that obtained mesh is strongly regular, i.e. there exists a positive constant ζ independent of the mesh size h such that for every element edges d, d' from the decomposition $\mathcal{E}_h$ is $d'/d\geq\zeta$. Denote by η the minimum angle of the triangulation obtained as a horizontal projection of the prismatic mesh.

The velocity function $\mathbf{u}$ will be approximated with the vector functions linear on every element $e\in\mathcal{E}_h$. We define the Raviart-Thomas space $\mathbf{RT}^0(e)$

$$\mathbf{RT}^0(e)=\{\mathbf{v}^e;\ \mathbf{v}^e(\mathbf{x})=\sum_{i=1}^{5}\nu_j\mathbf{v}_j(\mathbf{x}),\ \mathbf{x}\in e\}. \tag{3.1}$$

with linearly inependent basis functions $\mathbf{v}_j^e,\ j = 1, ..., 5$, of the form

$$\mathbf{v}_1^e = k_1^e \begin{bmatrix} 0 \\ 0 \\ x_3 - \alpha_{13}^e \end{bmatrix},\ \mathbf{v}_2^e = k_2^e \begin{bmatrix} 0 \\ 0 \\ x_3 - \alpha_{23}^e \end{bmatrix}, \tag{3.2}$$

$$\mathbf{v}_3^e = k_3^e \begin{bmatrix} x_1 - \alpha_{31}^e \\ x_2 - \alpha_{32}^e \\ \beta_3^e x_3 - \alpha_{33}^e \end{bmatrix},\ \mathbf{v}_4^e = k_4^e \begin{bmatrix} x_1 - \alpha_{41}^e \\ x_2 - \alpha_{42}^e \\ \beta_4^e x_3 - \alpha_{43}^e \end{bmatrix},\ \mathbf{v}_5^e = k_5^e \begin{bmatrix} x_1 - \alpha_{51}^e \\ x_2 - \alpha_{52}^e \\ \beta_5^e x_3 - \alpha_{53}^e \end{bmatrix}$$

such that

$$\mathcal{F}_j(\mathbf{v}_i^e) = \int_{f_j^e} \mathbf{n}_j^e \cdot \mathbf{v}_i^e dS = \ \delta_{ij},\ i, j = 1, ..., 5. \tag{3.3}$$

Here f_j^e denotes the j-th face of the element e and $\mathbf{n}_j^e$ its outward normal vector (with respect to the element e).

LEMMA 3.1: *The system of functional equations*

$$\mathcal{F}_j(\mathbf{v}_i^e) := \int_{f_j^e} \mathbf{n}_j^e \cdot \mathbf{v}_i^e dS = \delta_{ij},\ i, j = 1, \ldots, 5$$

generates the unique set of basis vector functions of the form (3.2).

PROOF: Substituting (3.2) into (3.3) we obtain

$$\int_{f_j^e} k_i^e \left[n_{j1}^e x_1 + n_{j2}^e x_2 + n_{j3}^e \beta_i^e x_3 - n_{j1}^e \alpha_{i1}^e - n_{j2}^e \alpha_{i2}^e - n_{j3}^e \alpha_{i3}^e\right] dS = \delta_{ij}. \tag{3.4}$$

For $i \neq j$ we get the condition

$$n_{j1}^e \alpha_{i1}^e + n_{j2}^e \alpha_{i2}^e + n_{j3}^e \alpha_{i3}^e - n_{j3}^e x_{T3}(f_j^e) \beta_i^e = n_{j1}^e x_{T1}(f_j^e) + n_{j2}^e x_{T2}(f_j^e),$$

where $\mathbf{x}_T(f_j^e)$ denotes the centre of gravity of the j-th face. Thus for $i = 1, 2$ we have

$$\alpha_{i3}^e = x_{T3}(f_j^e),\ i = 1, j = 2 \text{ or } i = 2, j = 1. \tag{3.5}$$

From (3.4) we obtain

$$k_i^e = \{n_{i3}^e [x_{T3}(f_i^e) - x_{T3}(f_j^e)] |f_i^e|\}^{-1}, \tag{3.6}$$

where $|f_i^e|$ denotes area of the i-th face, so $|f_i^e| > 0$. For $i = 3, 4, 5$ we obtain the system of equations for unknowns α_{i1}^e, α_{i2}^e, α_{i3}^e and β_i^e;

$$n_{j1}^e \alpha_{i1}^e + n_{j2}^e \alpha_{i2}^e + n_{j3}^e \alpha_{i3}^e - n_{j3}^e x_{T3}(f_j^e) \beta_i^e = n_{j1}^e x_{T1}(f_j^e) + n_{j2}^e x_{T2}(f_j^e) \qquad j = 1, 2 \tag{3.7}$$

$$n_{j1}^e \alpha_{i1}^e + n_{j2}^e \alpha_{i2}^e = n_{j1}^e x_{T1}(f_j^e) + n_{j2}^e x_{T2}(f_j^e) \qquad j = 3, 4, 5;\ j \neq i \quad . \tag{3.8}$$

Arbitrary two vectors from the set $\{\mathbf{n}_3^e, \mathbf{n}_4^e, \mathbf{n}_5^e\}$ are linearly indenpendent. Hence, the system (3.8) has a unique solution $\mathbf{a}_{i(1,2)}^e = (\alpha_{i1}^e, \alpha_{i2}^e)$. Consider the subdeterminant

$$n_{13}^e n_{23}^e \begin{vmatrix} 1 & -x_{T3}(f_1^e) \\ 1 & -x_{T3}(f_2^e) \end{vmatrix} = n_{13}^e n_{23}^e [x_{T3}(f_1^e) - x_{T3}(f_2^e)] \neq 0.$$

Then substituting for α_{i1}^e and α_{i2}^e, the system (3.7) has the unique solution $(\alpha_{i3}^e, \beta_i^e)$. For k_i^e we have

$$k_i^e[\mathbf{n}_i^e \cdot \mathbf{x}_i(f_i^e) - \mathbf{n}_i^e \cdot \mathbf{a}_{i(1,2)}^e]|f_i^e| = 1. \tag{3.9}$$

The coefficient k_i^e is invariant of the translation. We use translation of the element e to element $\hat{e}$ such that $x_3 = f_j^{\hat{e}} \cap f_i^{\hat{e}}$ for some $j \neq i$. Then the right hand side of the system (3.8) is equal zero, i.e. $n_{j1}^{\hat{e}} x_{T1}(f_j^{\hat{e}}) + n_{j2}^{\hat{e}} x_{T2}(f_j^{\hat{e}}) = 0$ and so $\mathbf{a}_{i(1,2)}^{\hat{e}} = (0,0)$. Estimate then

$$\mathbf{n}_i^{\hat{e}} \cdot \mathbf{x}_i(f_i^{\hat{e}}) \geq |\mathbf{n}_i^{\hat{e}}||\mathbf{x}_i(f_i^{\hat{e}})| \sin\eta > 0.$$

Therefore

$$k_i^e = k_i^{\hat{e}} = [\mathbf{n}_i^{\hat{e}} \cdot \mathbf{x}_i(f_i^{\hat{e}})]^{-1}|f_i^{\hat{e}}|^{-1} > 0.$$

$\square$

We define also

$$\mathbf{RT}_{-1}^0(\mathcal{E}_h) = \{\mathbf{v}_h \in \mathbf{L}^2(\Omega);\ \mathbf{v}_h^e \in \mathbf{RT}^0(e), \forall e \in \mathcal{E}_h\}, \tag{3.10}$$

the space that consists the vector functions linear on every element. We note that in the case of nonparallel bases these functions are not continuous across the interelement boundaries Γ_h. Denote the space of scalar functions constant on the element e by $M^0(e)$ with basis function of the form:

$$\phi_h^e(\mathbf{x}) = 1,\ \mathbf{x} \in e;\ \ \phi_h^e(\mathbf{x}) = 0,\ \mathbf{x} \notin e.$$

Then we introduce the space

$$M_{-1}^0(\mathcal{E}_h) = \{\phi_h \in L^2(\Omega);\ \phi_h^e \in M^0(e), \forall e \in \mathcal{E}_h\} \tag{3.11}$$

which consists element-wise constant functions that will approximate the piezometric potential p. Let $M^0(f)$ be the space of constant functions on the interelement face $f \in \Gamma_h$ and the space $M_{-1}^0(\Gamma_h)$ defined as

$$M_{-1}^0(\Gamma_h) = \{\mu_h : \Gamma_h \to R;\ \mu_h^f \in M^0(f), \forall f \in \Gamma_h\} \tag{3.12}$$

which consists the functions constant on every face from Γ_h. Further $p_{D,h}$, $u_{N,h}$ be the functions from $M_{-1}^0(\partial\Omega)$ which approximate the functions p_D and u_N given in the boundary conditions and which satisfy

$$\int_f (p_{D,h} - p_D)dS = 0;\ \forall f \in \partial\Omega_D, \tag{3.13}$$

$$\int_f (u_{N,h} - u_N)dS = 0;\ \forall f \in \partial\Omega_N. \tag{3.14}$$

Then the Raviart-Thomas approximation of the mixed-hybrid formulation for the problem reads as follows (we refer also to [9] or [10]):

$$find \;\; (\mathbf{u}_h, p_h, \lambda_h) \in \mathbf{RT}^0_{-1}(\mathcal{E}_h) \times M^0_{-1}(\mathcal{E}_h) \times M^0_{-1}(\Gamma_h) \; such \; that$$

$$\sum_{e\in\mathcal{E}_h} \{(\mathbf{A}^{-1}\mathbf{u}_h, \mathbf{v}_h)_{0,e} - (p_h, \nabla\cdot\mathbf{v}_h)_{0,e} + <\lambda_h, \mathbf{n}^e\cdot\mathbf{v}_h>_{\partial e\cap\Gamma_h}\} =$$
$$=< p_{D,h}, \mathbf{n}^e\cdot\mathbf{v}_h >_{\partial e}; \quad \forall \mathbf{v}_h \in \mathbf{RT}^0_{-1}(\mathcal{E}_h). \tag{3.15}$$

$$-\sum_{e\in\mathcal{E}_h} (\nabla\cdot\mathbf{u}_h, \phi_h)_{0,e} = -(q_h, \phi_h)_{0,\Omega}; \quad \forall\phi_h \in M^0_{-1}(\mathcal{E}_h). \tag{3.16}$$

$$\sum_{e\in\mathcal{E}_h} < \mathbf{n}^e\cdot\mathbf{u}_h, \mu_h >_{\partial e} =< u_{N,h}, \mu_h >_{\partial\Omega_N}; \quad \forall\mu_h \in M^0_{-1,D}(\Gamma_h). \tag{3.17}$$

Next, the system of linear equations equivalent to the problem (3.15) - (3.17) will be derived. Let $e_j \in \mathcal{E}_h$, $j = 1,\ldots,J$ be the numbered system of prismatic elements. On every element we have defined five-dimensional space $\mathbf{RT}^0(e)$ of linear vector functions $\mathbf{v}^e_i$, $i = 1,\ldots,5$. The finite-dimensional space $\mathbf{RT}^0_{-1}(\mathcal{E}_h)$ is then spanned by $5\times J$ linearly independent basis functions $\mathbf{v}_i$, $i = 1,\ldots,I = 5\times J$. Let f_k, $k = 1,\ldots,K$, be the numbered system of interelement faces from Γ_h. By introduced approximation, the functions $\mathbf{u}_h$, p_h and λ_h belong to spaces $\mathbf{RT}^0_{-1}(\mathcal{E}_h)$, $M^0_{-1}(\mathcal{E}_h)$ and $M^0_{-1}(\Gamma_h)$ respectively and so can be expanded in the form

$$\mathbf{u}_h(\mathbf{x}) = \sum_{i\in I} \tilde{u}_i\mathbf{v}_i(\mathbf{x}), \;\; p_h(\mathbf{x}) = \sum_{j\in J} \tilde{p}_j\phi_j(\mathbf{x}), \;\; \mathbf{x}\in\Omega,$$

$$\lambda_h(\mathbf{x}) = \sum_{k\in K} \tilde{\lambda}_k\mu_k(\mathbf{x}), \;\; \mathbf{x}\in\Gamma_h.$$

We denote by $u = (\tilde{u}_1, ..., \tilde{u}_I)^T$, $p = (\tilde{p}_1, ..., \tilde{p}_J)^T$, $\lambda = (\tilde{\lambda}_1, ..., \tilde{\lambda}_K)^T$ and

$$A_{ij} = (\mathbf{A}^{-1}\mathbf{v}_i, \mathbf{v}_j)_{0,\Omega}; \;\; i = 1,\ldots,I, \;\; j = 1,\ldots,I \tag{3.18}$$

$$B_{ij} = -(\nabla\cdot\mathbf{v}_i, 1)_{0,e_j}; \;\; i = 1,\ldots,I, \; j = 1,\ldots,J \tag{3.19}$$

$$C_{ik} =< \mathbf{n}_k\cdot\mathbf{v}_i, 1 >_{f_k}; \;\; i = 1,\ldots,I, \; k = 1,\ldots,K. \tag{3.20}$$

Here $\mathbf{n}_k$ is the outward normal vector to the face f_k with respect to the element corresponding to the support of the function $\mathbf{v}_i$. Then we compute

$$[q_1]_i \;\; = \;\; - < p_{D,h}, \mathbf{n}_i\cdot\mathbf{v}_i >_{\partial\Omega_D}; \;\; i = 1,\ldots,I, \tag{3.21}$$
$$[q_2]_j \;\; = \;\; -(q, 1)_{0,e_j}; \;\; j = 1,\ldots,J, \tag{3.22}$$
$$[q_3]_k \;\; = \;\; < u_{N,h}, 1 >_{f_k}; \;\; k = 1,\ldots,K. \tag{3.23}$$

Substituting $\mathbf{u}_h$, p_h and λ_h into (3.15) - (3.17) we can now write the system of linear equations

$$\begin{pmatrix} A & B & C \\ B^T & & \\ C^T & & \end{pmatrix} \begin{pmatrix} u \\ p \\ \lambda \end{pmatrix} = \begin{pmatrix} q_1 \\ q_2 \\ q_3 \end{pmatrix}. \tag{3.24}$$

LEMMA 3.2: *Assuming $\partial\Omega_D \neq \emptyset$ the matrix $(B \quad C) \in R^{I,J+K}$ defined in (3.19) and (3.20) has full column rank, i.e. rank $(B \quad C) = J + K$.*

PROOF: Suppose $Bp + C\lambda = 0$ holds for some vectors p and λ. Then $v^T(Bp + C\lambda) = 0, \ \forall v \in R^I$. Equivalently, we have

$$-\sum_{e\in\mathcal{E}_h} (\nabla\cdot\mathbf{v}, p)_{0,e} + \sum_{e\in\mathcal{E}_h} < \mathbf{n}^e\cdot\mathbf{v}, \lambda >_{\partial e\cap\Gamma_h} = 0, \ \forall\mathbf{v}\in\mathbf{RT}^0_{-1}(\mathcal{E}_h)\,. \tag{3.25}$$

Using the Green formula on the first term in (3.25) we have for all $\mathbf{v}\in\mathbf{RT}^0_{-1}(\mathcal{E}_h)$

$$\begin{aligned} &-\sum_{e\in\mathcal{E}_h} < \mathbf{n}^e\cdot\mathbf{v}, p >_{\partial e} + \sum_{e\in\mathcal{E}_h} < \mathbf{n}^e\cdot\mathbf{v}, \lambda >_{\partial e\cap\Gamma_h} = \\ &= \sum_{e\in\mathcal{E}_h} < \mathbf{n}^e\cdot\mathbf{v}, \lambda - p >_{\partial e\cap\Gamma_h} - \sum_{e\in\mathcal{E}_h} < \mathbf{n}^e\cdot\mathbf{v}, p >_{\partial e\cap\partial\Omega_D} = 0. \end{aligned} \tag{3.26}$$

Because Dirichlet boundary condition is defined at least one face from $\partial\Omega_D$, there exists $\bar{e}\in\mathcal{E}_h$ such that $\partial\bar{e}\cap\partial\Omega_D\neq\emptyset$. Then for some $\bar{\mathbf{v}}$, $\bar{e}\subset supp(\bar{\mathbf{v}})$ we have $< \mathbf{n}^{\bar{e}}\cdot\mathbf{v}, p >_{\partial\bar{e}\cap\partial\Omega_D} = 0$ and so $p = 0$ on $\bar{e}$. Consequently $p = 0$ also on some faces belonging to Γ_h. Since the first sum in (3.26) implies $\lambda = p$ on Γ_h we get $p = 0$ on all $e\in\mathcal{E}_h$ and $\lambda = 0$ on all $f\in\Gamma_h$. □

4 The solution of the discretized linear system

A considerable interest has been devoted to the solution of the set of linear equations (3.24) in recent years. These systems arise frequently, e.g. from mixed finite element or finite difference discretizations of Stokes equations in computational fluid dynamics or other second order elliptic problems.

We will briefly recall some possible ways in the solution of (3.24) and particularly we will concentrate on some approaches, which we consider to be promising.

Consider first the Uzawa-like approach (see [6], [5]), often advocated as an efficient solution technique. These algorithms are in fact variants of some classical iterative schemes applied to the system of linear equations. As an example, the inexact Uzawa scheme for (3.24) uses the splitting matrix of the form

$$M = \begin{pmatrix} Q_A & & \\ B^T & \frac{1}{\alpha}Q_{MB} & \\ C^T & & \frac{1}{\beta}Q_{MC} \end{pmatrix}, \tag{4.1}$$

where Q_A is an approximation of the matrix A; Q_{MB} and Q_{MC} are some preconditioning matrices and α, β are fixed parameters. This leads to the iterative scheme:

$$
\begin{aligned}
u_{i+1} &= u_i + Q_A^{-1}(q_1 - (Au_i + Bp_i + C\lambda_i)) \\
p_{i+1} &= p_i + \alpha Q_{MB}^{-1}(q_2 - B^T u_{i+1}) \\
\lambda_{i+1} &= \lambda_i + \beta Q_{MC}^{-1}(q_3 - C^T u_{i+1})
\end{aligned}
$$

Note that in the "exact" case ($Q_A = A$) this is a first order Richardson iteration with the two fixed parameters applied to the Schur complement system for unknowns $(p^T, \lambda^T)^T$ preconditioned by the matrix $diag(Q_{MB}, Q_{MC})$.

Since the Uzawa-like algorithms are stationary iterative methods, it is only natural to apply the standard and powerful nonstationary conjugate gradient method for the solution of the systems with symmetric positive definite matrix (see [8]). We have two possible ways to reduce the problem (3.24) to subproblems with symmetric and positive definite matrix. We can use a partial substitution for the unknown u to obtain the Schur complement system for the unknowns $(p^T, \lambda^T)^T$. This approach was discussed in [9]. Similarly, two successive substitutions were used in [2], where Schur complement system for the unknown vector λ was solved.

Although block diagonal block matrix can be easily invertible in the scalar computing environment, another efficient strategy may be based on the solution of the global system (3.24) by the preconditioned conjugate gradient method. The system (3.24) is, however, symmetric indefinite. Motivated by [3] and [5] suppose that Q_A satisfies

$$1 < \alpha_1 \leq \frac{(v, Av)}{(v, Q_A, v)} \leq \alpha_2$$

and let Q_T be an approximation of the matrix T

$$T = \begin{pmatrix} (A - Q_A)Q_A^{-1}A & (A - Q_A)Q_A^{-1}B \\ B^T Q_A^{-1}(A - Q_A) & B^T Q_A^{-1} B \end{pmatrix},$$

such that

$$1 < \beta_1 \leq \frac{(v, Tv)}{(v, Q_T, v)} \leq \beta_2.$$

Then the product of matrices

$$\begin{pmatrix} A - Q_A & & \\ & I & \\ & & I \end{pmatrix} \begin{pmatrix} Q_A^{-1} & & \\ B^T Q_A^{-1} & -I & \\ C^T Q_A^{-1} & & -I \end{pmatrix} \begin{pmatrix} A & B & C \\ B^T & & \\ C^T & & \end{pmatrix} \tag{4.2}$$

is symmetric positive definite matrix (see [3]). Premultiplying (4.2) by the matrix

$$\begin{pmatrix} Q_T^{-1} & \\ C^T Q_A^{-1} \,(\, A - Q_A \quad B \,)\, Q_T^{-1} & -I \end{pmatrix}$$

we obtain symmetric positive matrix with respect to the inner product

$$\left[\begin{pmatrix} x \\ p \\ \lambda \end{pmatrix}, \begin{pmatrix} \tilde{x} \\ \tilde{p} \\ \tilde{\lambda} \end{pmatrix} \right] = \left(T \begin{pmatrix} x \\ p \end{pmatrix}, \begin{pmatrix} \tilde{x} \\ \tilde{p} \end{pmatrix} \right) - \left(Q_T \begin{pmatrix} x \\ p \end{pmatrix}, \begin{pmatrix} \tilde{x} \\ \tilde{p} \end{pmatrix} \right) + (\lambda, \tilde{\lambda}).$$

Consequently, the matrix of the system (3.24) is symmetrizable and following Hageman-Young [7] we can apply the conjugate gradient method.

Another conjugate gradient-type method, which can be applied also to symmetric indefinite system is MINRES method presented in [13]. This strategy, based on the preconditioned MINRES scheme has been tested in [14] and [15], where different types of preconditioners were investigated. Our preconditioner is based on the incomplete Bunch-Parlett decomposition of (3.24), which is obtained from the left-looking algorithm based on the directed graph model (see [1]) to get a structure of the rows of the Bunch-Parlett factor L.

Detailed results of numerical experiments and comparison of different approaches used in our underground water flow applications will be published in the forthcoming paper [11].

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