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# Slightly generalized regular space decompositions

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Space decomposition methods represent an important part of numerical modelling process. In many applications it is suitable to use the simplest case of decomposition – regular rectangular grid: the whole raster graphic concept can be seen from this point of view. Different raster concept, based on regular hexagonal mesh, is analyzed e.g. in [18]. Generalized task – decomposition of the space to the set of the identical elements have been presented in various research areas since a long time, and it is connected with Hilbert’s 18th problem [9], [10].

Within the numerical methods development, the space discretization became an important tool of the shape expressivity. The domain of interest is decomposed to simple polyhedral elements. In the simplest case of linear approximation, the triangles for 2D tasks and tetrahedra for 3D tasks are used. There is a wide range of generators used for the decomposition, e.g. [7], [6], which produces meshes with irregular structure of nodes coincidence. For good interpolation properties, the condition like Delaunay one [3], [5] is required in the case of the isotropical environment. (In 2D case, the Delaunay triangulation maximizes the minimum angle. Compared to any other triangulation of the points, the smallest angle in the Delaunay triangulation is at least as large as the smallest angle in any other. However, the Delaunay triangulation does not necessarily minimize the maximum angle.)

Due to the fact, that for geometric modelling (CAD) parametrical models based on the tool of NURBS curves, surfaces and volumes are used, discretization with regular structure of node coincidence is important and wide spread. Moreover, the common basis for both geometric and physically based modelling can be founded [11], [4].

Using current methods, creating 3D models is an extremely time-consuming, unreliable, and labour-intensive process. So, when the geometry information is obtained e.g. from computer tomograph or similar devices, i.e. in the form of pixel/voxel grid, it is reasonable to create the space decomposition in the same or similar way. The discretization error – aliasing – has a very local character in this case only [2]. Moreover, this error can be eliminated as mentioned below.

**Finer mesh** This way, however, leads to substantial increasing of memory demands.

**Adjusting the geometry** Some of the grid nodes are shifted according to prescribed geometry. It is proved [16] that even in the simplest case of adjusting (local displacement of the grid nodes only, which are the most close to the prescribed shape) resulting mesh holds the Delaunay property.

**Pixel/voxel partitioning** This approach gives a wide variability of the shape expression: from four types of possible tetrahedra we can create 72 different conform decompositions [12], [1], [17]. On the other hand, not all configurations of diagonals are admissible: in some cases only nonconform decompositions are possible, and in some cases no decompositions are possible. This fact can be considered as a generalization of the decomposition of Schönhardt’s polyhedron [19], [20]. This drawback can be eliminated. We can move the node in such way, that planar quadrilateral, which is nonconformly partitioned, become a tetrahedron. In this case voxel can be decomposed to 6-13 tetrahedra. [13]. So, in this case both regularity of geometry and nodes coincidence is spoilt.

**Goldberg's tiling** There are several methods how to decompose 3D space into the set of the same tetrahedra [8], [9], [21]. Comparison of these decompositions in [14] shows the benefit of Goldbergs tiling. Within this class of decompositions we can find such one, based on tetrahedron, close to the regular one (each face is isoscelles triangle with edges ratio  $\sqrt{\frac{4}{3}} : 1 : 1$ ). Moreover, Cartesian indexation of nodes with three-indexes can be used and there are four different assembling schemes how we can compose the voxel form these six tetrahedra [15].

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